

Paper: Fair Mixup: Fairness via Interpolation [1]

Jiaxin Liu

Group Reading

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Overview

- 1 Introduction
- 2 Group Fairness
- 3 Dynamic Formulation of Fairness
- 4 Fair Mixup
- 5 Experiments

- Fairness in ML.

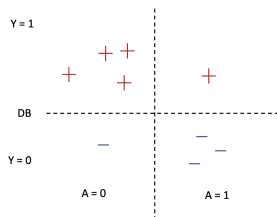


Figure: Fairness example.

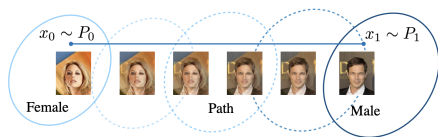


Figure: Interpolation example.

- Optimization problem:

$$\min_f \mathbb{E}_{(x,y) \sim P} [l(f(x), y)] + \lambda \cdot \text{fairness measurements}$$

- **For a binary classification setup**
 - Inputs $X \in \mathcal{X} \subset \mathbb{R}^d$.
 - Labels $Y \in \mathcal{Y} = \{0, 1\}$
 - Sensitive attribute $A \in \{0, 1\}$.
 - $\hat{Y} \in [0, 1]$ from model $f : \mathbb{R}^d \rightarrow [0, 1]$

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- **Demographic parity (DP)**

- $P(\hat{Y}|A=0) = P(\hat{Y}|A=1)$
- requires \hat{Y} to be independent of A .

- **Equalized odds (EO)**

- $P(\hat{Y}|A=1, Y=y) = P(\hat{Y}|A=0, Y=y)$ for $y \in \{0, 1\}$
- requires \hat{Y} and A to be conditionally independent w.r.t. Y .

- $\Delta\mathbf{DP}(\mathbf{f}) = |\mathbb{E}_{x \sim P_0} f(x) - \mathbb{E}_{x \sim P_1} f(x)|$
- $\Delta\mathbf{EO}(\mathbf{f}) = \sum_{y \in \{0,1\}} |\mathbb{E}_{x \sim P_0^y} f(x) - \mathbb{E}_{x \sim P_1^y} f(x)|$

where $P_a = P(\cdot | A = a)$ and $P_a^y = P(\cdot | A = a, Y = y)$, $a, y \in \{0, 1\}$.

Gap Regularization

$$\min_f \mathbb{E}_{(x,y) \sim P} [l(f(x), y)] + \lambda \Delta\mathbf{DP}(f)$$

where l is the classification loss.

Data augmentation

- Mixup [3]: generate samples via convex combinations of pairs of examples.
 - $z_i, z_j \in \mathbb{R}^d$
 - virtual samples $tz_i + (1 - t)z_j$ for $t \in [0, 1]$.

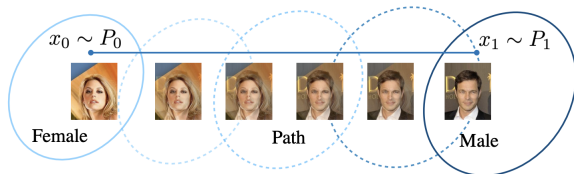


Figure: Example for interpolation.

Dynamic Formulation of fairness

- Interpolator $T(x_0, x_1, t)$ between x_0 and x_1 based on step t .
 - $T(x_0, x_1, 0) = x_0$
 - $T(x_0, x_1, 1) = x_1$
- $\Delta\mathbf{DP}(\mathbf{f}) = |\mathbb{E}_{x \sim P_0} f(x) - \mathbb{E}_{x \sim P_1} f(x)|$

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Lemma 1.

Let $T : \mathcal{X}^2 \times [0, 1] \rightarrow \mathcal{X}$ be a function continuously differentiable w.r.t. t such that $T(x_0, x_1, 0) = x_0$ and $T(x_0, x_1, 1) = x_1$. For any differentiable function f , we have

$$\Delta\text{DP}(f) = \left| \int_0^1 \frac{d}{dt} \int f(T(x_0, x_1, t)) dP_0(x_0) dP_1(x_1) dt \right| =: \left| \int_0^1 \frac{d}{dt} \mu_f(t) dt \right|$$

where we define $\mu_f(t) = \mathbb{E}_{x_0 \sim P_0, x_1 \sim P_1} f(T(x_0, x_1, t))$, the expected output of f w.r.t. $T(x_0, x_1, t)$.



Smoothness Regularization

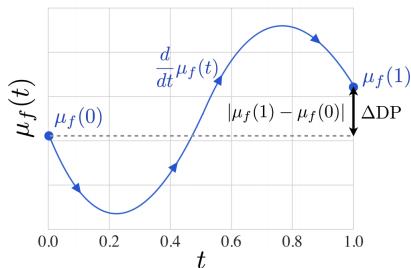


Figure: $\mu_f(t) - t$ figure.

- $\mu_f(t) = \mathbb{E}_{x_0 \sim P_0, x_1 \sim P_1} f(T(x_0, x_1, t))$

Smoothness Regularizer

$$R_T(f) = \int_0^1 \left| \frac{d}{dt} \mu_f(t) \right| dt \geq \Delta DP(f)$$

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Input Mixup

Smoothness regularizer:

$$R_{\text{mixup}}^{\text{DP}}(f) = \int_0^1 \left| \int \langle \nabla_x f(tx_0 + (1-t)x_1), x_0 - x_1 \rangle dP_0(x_0)dP_1(x_1) \right| dt.$$

- Manifold Mixup [2]
 - Compositional hypothesis $f \circ g$
 - feature encoder $g : \mathcal{X} \rightarrow \mathcal{Z}$
 - predictor $f : \mathcal{Z} \rightarrow \mathcal{Y}$

-

$$\begin{aligned}\Delta DP(f \circ g) &= \left| \int_0^1 \frac{d}{dt} \int f(T(x_0, x_1, t)) dP_0(x_0) dP_1(x_1) dt \right| \\ &= \left| \int_0^1 \frac{d}{dt} \int f(tg(x_0) + (1-t)g(x_1)) dP_0(x_0) dP_1(x_1) dt \right|\end{aligned}$$

Smoothness Regularizer

Input Mixup

Smoothness regularizer:

$$R_{\text{mixup}}^{\text{DP}}(f) = \int_0^1 \left| \int \langle \nabla_x f(tx_0 + (1-t)x_1), x_0 - x_1 \rangle dP_0(x_0)dP_1(x_1) \right| dt.$$

Manifold Mixup

Smoothness regularizer:

$$\begin{aligned} R_{\text{mixup}}^{\text{DP}}(f) \\ = \int_0^1 \left| \int \langle \nabla_z f(tg(x_0) + (1-t)g(x_1)), g(x_0) - g(x_1) \rangle dP_0(x_0)dP_1(x_1) \right| dt. \end{aligned}$$

Equalized Odds (EO)

- $\Delta \mathbf{EO}(f) = \sum_{y \in \{0,1\}} |\mathbb{E}_{x \sim P_0^y} f(x) - \mathbb{E}_{x \sim P_1^y} f(x)|$
- $\Delta \mathbf{EO}(f) = \sum_{y \in \{0,1\}} \left| \int_0^1 \frac{d}{dt} \int f(T(x_0, x_1, t)) dP_0^y(x_0) dP_1^y(x_1) dt \right|$

Input Mixup

Smoothness regularizer:

$$R_{\text{mixup}}^{\text{EO}}(f) = \sum_{y \in \{0,1\}} \int_0^1 \left| \int \langle \nabla_x f(tx_0 + (1-t)x_1), x_0 - x_1 \rangle dP_0^y(x_0) dP_1^y(x_1) \right| dt.$$

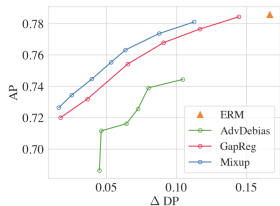
Optimization Problem

Fair Mixup:

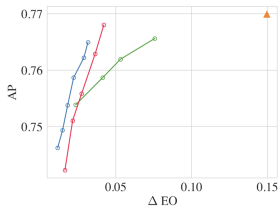
$$\min_f \mathbb{E}_{(x,y) \sim P} [l(f(x), y)] + \lambda R_{\text{mixup}}(f)$$

Experiments

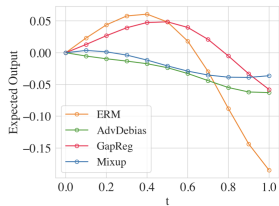
Task 1: predict income \sim \$50k; attribute: gender.



(a) Demographic Parity



(b) Equalized Odds



(c) Path Visualization

Figure: Adult Dataset. Task 1

Experiments

Task 2: celebrity faces 2.1 attractive, 2.2 smile, 2.3 wavy hair. Attribute: gender.

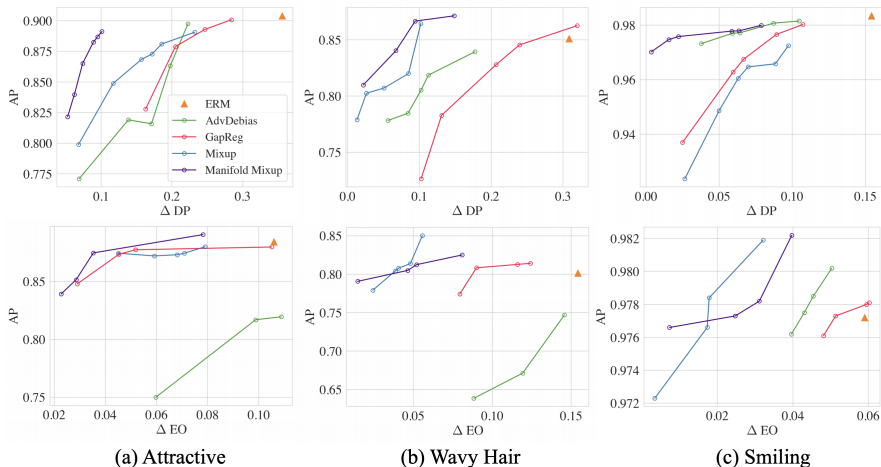


Figure: CelebA Dataset. Task 2

Task 2: Visualization of calibrated paths

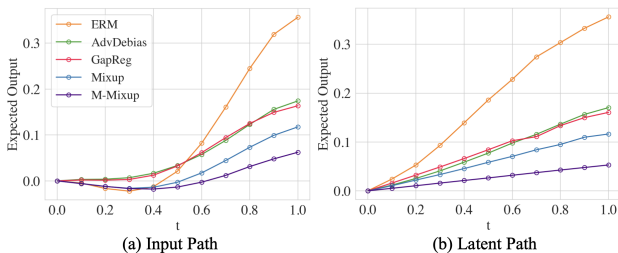


Figure: CelebA Dataset. Task 2.1 attractive classification.